

2/21/01

Lec. 18 Generalized Stat. Interpretation

Example of eigenstate

$$\hat{H}|\psi\rangle = E|\psi\rangle$$

Eigenstates have zero uncert.

$$\begin{aligned} \sigma_E^2 &= \langle (\hat{H} - \langle \hat{H} \rangle)^2 \rangle = \langle \hat{H}^2 \rangle - \langle \hat{H} \rangle^2 \\ &= E^2 - E^2 \end{aligned}$$

3' If you measure an observable \hat{Q} on a particle in the state $|\psi\rangle$, you are certain to get one of the eigenvalues of \hat{Q} . Example: energy of H osc. must be $(N + \frac{1}{2})\hbar\omega$. The probability of getting the particular eigenvalue λ is equal to the absolute square of the λ component of $|\psi\rangle$ when expressed in the orthonormal basis of eigenvectors.

Two kinds of eigenvectors
a) Discrete spectrum (H. Osc., particle in a box...)

$$\hat{Q} |e_n\rangle = \lambda_n |e_n\rangle \quad n=1, 2, 3, \dots$$

$$\langle e_n | e_m \rangle = \delta_{nm}$$

$$|\psi\rangle = \sum_{n=1}^{\infty} c_n |e_n\rangle$$

$$|c_n|^2 = |\langle e_n | \psi \rangle|^2 \quad \text{prob. to get } \lambda_n$$

b) Continuous spectrum

$$\hat{Q} |e_k\rangle = \lambda_k |e_k\rangle \quad -\infty < k < \infty$$

Delta function norm

$$\langle e_k | e_p \rangle = \delta(k-l)$$

$$|\Psi\rangle = \int_{-\infty}^{\infty} c_k |e_k\rangle dk$$

$$c_k = \langle e_k | \Psi \rangle$$

Prob. to get k between k and $k+dk$

$$|c_k|^2 dk = |\langle e_k | \Psi \rangle|^2 dk$$

Example: position eigenstates

$$e_{x'}(x) = \delta(x-x')$$

$$c_{x'} = \langle e_{x'} | \Psi \rangle = \int \delta(x-x') \Psi(x,t) dx = \Psi(x',t)$$

Prob. to find particle between x' and $x'+dx'$

$$|c_{x'}|^2 dx' = |\Psi(x',t)|^2 dx'$$

Example: momentum eigenstates

$$e_p(x) = \frac{1}{\sqrt{2\pi\hbar}} e^{ipx/\hbar} \quad -\infty < p < \infty$$

The p component of $|\Psi\rangle$ is

$$c_p = \langle e_p | \Psi \rangle = \frac{1}{\sqrt{2\pi\hbar}} \int_{-\infty}^{\infty} e^{-ipx/\hbar} \Psi(x,t) dx$$

$$\equiv \Phi(p,t)$$

$$|c_p|^2 dp = |\Phi|^2 dp$$

momentum space wave function
prob. to have mom. between p and $p+dp$

The state of the system is described by

$|\Psi\rangle$
 This is an abstract vector in the Hilbert space. You chose a representation position space and deal with wave functions, ... and deal with momentum space, ... are dot products of $|\Psi\rangle$ with appropriate basis vectors

$$\Psi(x,t) \equiv \langle e_x | \Psi \rangle$$

$$\Phi(p,t) \equiv \langle e_p | \Psi \rangle$$

...

Uncertainty Principle

Consider any observable A

$$\begin{aligned} \sigma_A^2 &= \langle (\hat{A} - \langle A \rangle) \Psi | (\hat{A} - \langle A \rangle) \Psi \rangle \\ &= \langle \hat{A}^2 \rangle - \langle A \rangle^2 \end{aligned}$$

From $\langle \Psi | (\hat{A} - \langle A \rangle)^2 \Psi \rangle$ and $\hat{A} - \langle A \rangle$ is Hermitian

$$|F\rangle \equiv (\hat{A} - \langle A \rangle) |\Psi\rangle$$

$$\sigma_A^2 = \langle F | F \rangle$$

$$\sigma_B^2 = \langle g | g \rangle \quad \text{with} \quad |g\rangle \equiv (\hat{B} - \langle B \rangle) |\Psi\rangle$$

$$\sigma_A^2 \sigma_B^2 = \langle F | F \rangle \langle g | g \rangle \geq |\langle F | g \rangle|^2$$

$$|Z|^2 = \text{Re } Z^2 + \text{Im } Z^2 \geq \text{Im } Z^2 = \left[\frac{1}{2i} (Z - Z^*) \right]^2$$

let $z = \langle F | g \rangle$

$$\sigma_A^2 \sigma_B^2 \geq \left\{ \frac{1}{2i} [\langle F | g \rangle - \langle g | F \rangle] \right\}^2$$

$$\langle F | g \rangle = \langle (A - \langle A \rangle) \Psi | (B - \langle B \rangle) \Psi \rangle$$

$$= \langle \Psi | (A - \langle A \rangle) (B - \langle B \rangle) \Psi \rangle$$

$$= \langle \hat{A} \hat{B} \rangle - \langle A \rangle \langle B \rangle + \langle A \rangle \langle B \rangle - \langle A \rangle \langle B \rangle$$

$$= \langle \hat{A} \hat{B} \rangle - \langle A \rangle \langle B \rangle$$

$$\langle g | F \rangle = \langle \hat{B} \hat{A} \rangle - \langle A \rangle \langle B \rangle$$

so $\langle F | g \rangle - \langle g | F \rangle = \langle \hat{A} \hat{B} \rangle - \langle \hat{B} \hat{A} \rangle$

Commutator $[A, B] \equiv [AB - BA]$

$$\sigma_A^2 \sigma_B^2 \geq \left(\frac{1}{2i} \langle [\hat{A}, \hat{B}] \rangle \right)^2$$

Generalized Uncertainty Principle

Example $A = x$ $B = p$

$$[\hat{x}, \hat{p}] = \left[x \frac{\hbar}{i} \frac{\partial}{\partial x} - \frac{\hbar}{i} \frac{\partial}{\partial x} x \right]$$

$$[\hat{x}, \hat{p}] f(x) = x \frac{\hbar}{i} f' - \frac{\hbar}{i} \frac{\partial}{\partial x} (x f)$$

test function

$$= -\frac{\hbar}{i} f$$

$$[\hat{x}, \hat{p}] = -\frac{\hbar}{i} = i\hbar$$

$$\sigma_x^2 \sigma_p^2 \geq \left(\frac{\hbar}{2} \right)^2 \Rightarrow \left(\frac{\hbar}{2} \right)^2$$

$\sigma_x \sigma_p \geq \frac{\hbar}{2}$

$$\Rightarrow$$